Applied Numerical Analysis – AE2220-I – Quiz #3

Modules 5 and 6 - April, 2022

DO NOT OPEN UNTIL ASKED

Instructions:

- Make sure you have a machine-readable "Answer sheet".
- Use a black or blue pen to fill in the answer form.
- Write your name and student number on the answer sheet.
- $\bullet\,$ Fill in the answer form ${\bf neatly}$ to avoid risk of incorrect marking.
- Each question has exactly one correct answer.
- Correct answers will receive 5 points, unanswered questions 1 point, incorrect answers 0 points.
- Graphical calculators of all kinds are not allowed; a scientific calculator is recommended.
- This quiz has 10 questions and 4 pages (2 sheets) in total.

Numerical solution of ODEs

Question 1 Consider the equation of the harmonic damped oscillator with an external time dependent forcing:

$$x'' + x' + x = \sin(t^2)$$

with the initial-conditions x(0) = 0 and x'(0) = 2. Applying forward-Euler method with a timestep $\Delta t = \frac{1}{2}$, what is the position x_1 and the velocity x'_1 after one iteration?

A: UnansweredC: $x_1 = x_1' = 0.5$ E: $x_1 = x_1' = -0.5$ B: $x_1 = x_1' = 1.0$ D: $x_1 = x_1' = 0.0$ F: $x_1 = x_1' = -1.0$

Question 2 Consider the ODE u' = -2cu with initial condition u(0) = 1 and constant c > 0. Using backward-Euler and $\Delta t = \frac{1}{2}$, what is the approximation of u(4)?

A: Unanswered C: $(1 + c/2)^8$ E: $(1 - c/2)^8$ G: $(c/2)^8$ B: $(1 + c)^{-8}$ D: $(1 - c)^{-8}$ F: $(c)^{-8}$

Question 3 We're concerned with solving the ODE u' = f(u). Consider the scheme:

$$u_{i+1} = u_i + \frac{3}{2}\Delta t f(u_i) - \frac{1}{2}\Delta t f(u_{i-1}),$$

where u_i and u_{i-1} are known, and u_{i+1} is unknown. What is the *local*-truncation error of this scheme? [Hint: Use Taylor expansions of all terms; for the term $f(u_{i-1})$ expand first u_{i-1} , then f of the first two terms in the expansion.]

A: UnansweredC: Δt^0 E: Δt^2 G: Δt^4 B: Δt^{-1} D: Δt^1 F: Δt^3 H: Δt^5

Question 4 (Module 5 - ODEs) Consider the ODE y' = -ay with a > 0. Using the forward-Euler scheme we can write:

$$y_{i+1} = y_i + h(-ay_i)$$

By writing the solution at y_{i+1} in terms of the initial condition y_0 , or otherwise, decide for what range of stepsize h is the scheme stable for this equation?

A: UnansweredC: Always stableE: 0 < h < 1/aG: 0 < h < 2/aB: Never stableD: h > 0F: 0 < h < aH: 0 < h < 2a

Question 5 Consider the following multi-stage time-stepping scheme:

$$y_{n+1} = y_n + \frac{1}{2}h(k_1 + k_2),$$

$$k_1 = f(y_n),$$

$$k_2 = f(y_n + hk_1).$$

This scheme is known as the 2nd-order Runge-Kutta method. Assume for simplicity that f(y) = cy, with c a constant. Let z = ch. For what values of z is the scheme stable?

A:	Unanswered	E:	$ 1+z+\frac{1}{2}z^2+\frac{1}{12}z^3 < 1$
B:	1+z < 1	F:	$ 1+z+z^2 < 1^2$
\mathbf{C} :	1 - z < 1	G:	1+2z < 1
D:	$ 1 + z + \frac{1}{2}z^2 < 1$	H:	$ 1 + z + z^2 + \frac{1}{24}z^3 < 1$

Question 6 Consider a general time-stepping scheme $y_{i+1} = \mathcal{Q}(y_i)$ applied to an initial-value problem y' = f(y) with exact solution y(t). For example forward-Euler corresponds to $\mathcal{Q}(y) = y + hf(y)$. Let the scheme predict a discrete solution y_i at time t_i . Which of the following statements are true?

- (i) The global-truncation error at time t_i is $|y(t_i) y_i|$.
- (ii) The local-truncation error at time t_i is $|y'(t_i) \mathcal{Q}(y(t_i))|$.
- (iii) If y(t) is a degree-2 polynomial, and Q has local-truncation error proportional to h^3 , then $y(t_i) = \boldsymbol{y}_i$ for any Q.
- A: UnansweredD: (ii)G: (ii) and (iii)B: NoneE: (i) and (ii)H: (i), (ii) and (iii)C: (i)F: (i) and (iii)

Numerical optimization

Question 7 Consider the following function:

$$f(x,y) = -x^3 - y^2 + 3x - 3xy$$

Newton's method for *optimization* is applied and the following point extremal point (x, y) = (2, -3) is found. What can be said about this point? It is:

A: UnansweredB: A global maximumC: A global minimumD: A local maximum

- E: A local minimum
- F: A saddle-point
- G: Not extremal

Question 8 A rectangular cold storage box with *square* base of edge length l meters, height h meters and perfectly insulated top has a total volume of 10 m^3 . All other sides are uninsulated. The goal is to find l such that heat loss is minimized.

Apply Newton's method for optimization to minimize a suitable objective function (assume heat loss is proportional to surface area). Perform the update in terms of l, starting with an initial estimate $l_0 = 1.0$. What is l_1 to two decimal places?

A: Unanswered	C: 1.46	E: 1.23	G: 2.46
B: 0.46	D: 1.19	F: 0.54	H: 1.54

Question 9 Apply 1 iteration of the steepest descent method to the quadratic form

$$Q(\mathbf{x}) = \frac{1}{2}\mathbf{x}^T \cdot A \cdot \mathbf{x} + \mathbf{b}^T \cdot \mathbf{x} + c,$$

where

$$A = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}, \quad b = \begin{pmatrix} -1 \\ 4 \end{pmatrix}, \quad c = 5.$$

with the initial condition $x_0 = (1, 1)$. What is steepest descent direction?

A: Unanswered	C: $(1, 7)$	E: $(7, 1)$	G: $(3, -1)$
B: $(-1, -7)$	D: $(-7, -1)$	F: $(-3, 1)$	H: $(-1, 3)$

Question 10 The steepest descent method is applied to the quadratic form

$$Q(\boldsymbol{x}) = -\frac{1}{2}\boldsymbol{x}^T \cdot \boldsymbol{A} \cdot \boldsymbol{x} - \boldsymbol{b}^T \cdot \boldsymbol{x} + c$$

where A, b and c, are matrix, vector and scalar constants. Under what condition on the matrix A does the steepest descent method converge to the exact minimum in 1 iteration, from *any* initial condition \boldsymbol{x}_0 ? [Hint: If the initial search line $x_0 + \alpha d_0$ includes the exact minimum of $Q(\boldsymbol{x})$, then the method will converge in 1 iteration.]

- A: Unanswered
- B: A is a multiple of the identity matrix
- C: A is diagonal D: A is symmetric

- E: A is positive definite
- F: A has only positive eigenvalues
- G: A is equal to bb^T
- H: It always converges in 1 iteration

END OF EXAM