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# Applied Numerical Analysis – AE2220-I – Quiz #2

Modules 3 and 4 – Friday 15th March, 2019

DO NOT OPEN UNTIL ASKED

## Instructions:

- Make sure you have a machine-readable answer form.
- Write your name and student number on the answer form.
- Fill in the answer form **neatly** to avoid risk of incorrect marking.
- Fill in the **version number** of your quiz (see bottom right, 1-4) on the answer form.
- Use only **pencil** on the answer form, and correct with a rubber.
- This quiz requires a calculator.
- Each question has exactly one correct answer.
- Correct answers will receive 5 points, unanswered questions 1 point, incorrect answers 0 points.
- This quiz has **10 standard questions** and **4 pages (2 sheets)** in total.
- Question 11 is a bonus question, for extra points only.

## 1 Multi-dimensional interpolation

**Question 1** We wish to interpolate the function of  $M$  variables  $f(x_1, x_2, \dots, x_M)$ , with a tensor-product polynomial basis. We know *a priori* that the first  $P$  variables are the most important. Therefore to build the tensor-product basis, we use degree 5 polynomial approximations (1d) in each of the variables  $x_1, \dots, x_P$  individually, and degree 2 polynomial approximations in each of the variables  $x_{P+1}, \dots, x_M$  individually. How many basis functions are in the tensor-product basis in total?

- |                   |                   |                  |          |
|-------------------|-------------------|------------------|----------|
| A: Unanswered     | C: $P^5(M - P)^2$ | E: $6^P 3^{M-P}$ | G: $5^P$ |
| B: $P^6(M - P)^3$ | D: $5^P 2^{M-P}$  | F: $6^M$         | H: $6^P$ |

**Question 2** The function  $f(x, y)$  is interpolated at the points of the unit square  $x_0 = (-1, -1)$ ,  $x_1 = (1, -1)$ ,  $x_2 = (1, 1)$  and  $x_3 = (-1, 1)$ , in two ways:

- With a single rectangular patch on  $(x_0, x_1, x_2, x_3)$ , giving  $p_4(x, y)$
- With two triangular patches, on  $(x_0, x_1, x_2)$  and  $(x_2, x_3, x_0)$  separately, giving  $p_3(x, y)$

Which of the following statements are true, for  $x, y \in [-1, 1]$  and any  $f$ ? [Hint: The basis for  $p_4(x, y)$  is  $(1, x, y, xy)$ , the basis for  $p_3(x, y)$  is  $(1, x, y)$ .]

- I.  $p_4(-1, y) = p_3(-1, y)$   
 II.  $p_4(x, y) = p_3(x, y)$   
 III.  $p_4(x, 1) = p_3(x, 1)$

- |               |       |          |         |
|---------------|-------|----------|---------|
| A: Unanswered | C: I  | E: III   | G: I,II |
| B: All        | D: II | F: I,III | H: None |

**Question 3** Radial-basis interpolation is used to approximate  $f(x) = x$  in 1d using the nodes  $x_0 = -1$ ,  $x_1 = 1$ ,  $x_2 = 2$ , and the basis function  $\phi(r) = \exp(-r^2)$ . What is the value of the interpolant at  $x = 100$ , accurate to 2 significant figures?

- |               |        |        |
|---------------|--------|--------|
| A: Unanswered | C: 1.0 | E: 50  |
| B: 0.0        | D: 10  | F: 100 |

**Question 4** We create an interpolant  $s(x)$  for the function  $f(x) = 1 - \frac{1}{2}x^2$  using radial basis function interpolation. We use data points at  $x = 0, 1, 2$  and the following radial basis function:

$$\phi(r) = \begin{cases} 1 - \frac{r^2}{\theta^2} & \text{for } |r| \leq \theta \\ 0 & \text{for } |r| > \theta \end{cases}$$

The radial distance between a point  $x_i$  and a point  $x_j$  is defined as  $r = |x_i - x_j|$ , and  $\theta > 0$  is a tuning parameter. Which of the following statements is true?

- I.  $s(x) = f(x)$  for all  $x \in [-\theta, \theta]$  when  $\theta = \sqrt{2}$   
 II. When  $0 < \theta \leq 1$ , the system matrix A is the identity matrix  
 III. The 2nd-derivative of  $s(x)$  is constant

- |               |       |          |           |
|---------------|-------|----------|-----------|
| A: Unanswered | C: I  | E: I,II  | G: II,III |
| B: All        | D: II | F: I,III | H: None   |

## 2 Spline interpolation

**Question 5** Consider a generalized spline interpolant  $s(x)$  on the interval  $[0, 1]$ . The interval is divided into sub-intervals with  $N + 1$  nodes:

$$0 = x_0 < x_1 < \cdots < x_{N-1} < x_N = 1$$

at which sample data are given. Assume that the spline consists of polynomials of degree  $d$  on each interval, and that the spline is required to be  $d - 1$ -times continuously differentiable on the entire interval.

We impose 2 constraints at the boundaries:  $f''(0) = f''(1) = 0$ . What is the degree  $d$  of the polynomials needed to always be able to construct such a spline?

- |               |      |      |      |
|---------------|------|------|------|
| A: Unanswered | C: 4 | E: 6 | G: 8 |
| B: 3          | D: 5 | F: 7 | H: 9 |

## 3 Regression

**Question 6** Consider i) interpolation and ii) regression of a two-dimensional function  $f(\mathbf{x})$  where  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ . Assume that the approximating function  $p(\mathbf{x})$  in both cases is a linear combination of  $N$  distinct basis functions  $\phi_i(\mathbf{x})$ , and that  $f$  is sampled at  $M$  distinct locations. The interpolation conditions for i) lead to a system of linear equations, with system matrix  $A$ .

Consider the existence and uniqueness of solutions to these two problems. What condition is required on i) and ii) respectively, to guarantee unique solutions for each problem?

- A: Unanswered
- B: i) When  $M = N$ , and ii) when  $M \geq N$ .
- C: i) When  $\det(A) \geq 0$ , and ii)  $\det(A^T A) \geq 0$ .
- D: i) When  $\det(A) \neq 0$ , and ii)  $\det(A^T A) \neq 0$ .
- E: i) Always for polynomial  $\phi_i$ , and ii) polynomial  $\phi_i$ .
- F: i) Always for radial-basis functions  $\phi_i$ , and ii) polynomial  $\phi_i$ .
- G: i)  $A$  invertable, and ii)  $A$  symmetric.

**Question 7** Steady laminar flow through a channel with parallel walls has a *parabolic* velocity profile (“Poiseuille” flow). In a channel of height 2 on the interval  $y \in [-1, 1]$  we have two *approximate* measurements of the velocity, at  $y_0 = -\frac{1}{2}$  and  $y_1 = \frac{1}{2}$  with values  $v_0 = 7.3$  and  $v_1 = 8.7$ . In addition we know that the velocity at both channel walls is *exactly* zero (by the no-slip boundary condition), i.e.  $v(-1) = v(1) = 0$ . Derive and solve a mixed interpolation/regression problem to approximate  $v(y)$ , using a quadratic polynomial. What is the maximum velocity in the approximation of  $v$ ?

- |               |         |         |             |
|---------------|---------|---------|-------------|
| A: Unanswered | C: 26/3 | E: 36/5 | G: 38/5     |
| B: 25/3       | D: 32/3 | F: 37/5 | H: $\infty$ |

## 4 Numerical differentiation

**Question 8** One way of approximating derivatives is by rearranging a Taylor series. The Taylor approximation of  $f(x)$  about  $x_0$  is:

$$f(x_0 + h) = f(x_0) + f'(x_0)h + \frac{1}{2}f''(x_0)h^2 + \mathcal{O}(h^3),$$

where  $h := x - x_0$ . Assuming the value of  $f$  is known only at  $x_0$  and  $x_1$ , rearrange Taylor to get an approximate expression for  $f'(x_0)$ . What is the magnitude of the *error* in this approximation?

- A: Unanswered      C:  $\mathcal{O}(x_1 - x_0)$       E:  $\mathcal{O}(x_1 - x_0)^3$       G:  $\mathcal{O}(x_1 - x_0)^5$   
 B:  $\mathcal{O}(1)$       D:  $\mathcal{O}(x_1 - x_0)^2$       F:  $\mathcal{O}(x_1 - x_0)^4$

**Question 9** Assume you have obtained measurements of the lift coefficient of an aerofoil  $C_L(\alpha)$  at 3 different values of the angle of attack  $\alpha$ :  $C_L(-2) = -0.32$ ,  $C_L(0) = 0$ ,  $C_L(2) = 0.4$ . Which of the following techniques for estimating the derivative  $\frac{dC_L}{d\alpha}$  at  $\alpha = 0$  produces the same value?

- I. Central difference formula  
 II. Derivative of a least-squares linear regression  
 III. Derivative of a quadratic polynomial interpolant

- A: Unanswered      C: I, II      E: I, III  
 B: I, II and III      D: II, III      F: All give distinct answers

**Question 10** Consider this proposal for a finite difference scheme:

$$f'(x) = \frac{2f(x+2h) - f(x+h) - f(x)}{6h} + \epsilon.$$

How does the error  $\epsilon$  behave in terms of  $h$ ?

- A: Unanswered      C:  $\mathcal{O}(h)$       E:  $\mathcal{O}(h^2)$   
 B:  $\mathcal{O}(1)$  - inconsistent rule      D:  $\mathcal{O}(h^{1.5})$       F:  $\mathcal{O}(h^3)$

## 5 Bonus points

**Question 11** Today, 15th March 2019, there is a national strike in progress in the Netherlands. In which sector is this strike?

- A: Unanswered      E: Health care  
 B: Public transport      F: Education  
 C: Air-traffic control      G: Rubbish collection  
 D: Police      H: Dentistry

END OF EXAM